

algorithm is an extension of GS algorithm for flat-top footprint pattern synthesis that accounts for the HTA effects such as the material losses at each iteration. The solution is carried-out without applying iterations or extra-computation cost to overcome the high sidelobe level. We evaluate the performance of phase correction in the HTA and investigate its cross-polarization discrimination (XPD) in order to validate its polarization diversity capability.

2 Proposed anisotropic HTA Unit-Cell

In our recent work [2], we have demonstrated a broadband anisotropic unit-cell based on a gridded Jerusalem-cross (GJC), which combines the inductive and capacitive behavior, and facilitates an independent phase control for two orthogonal linear polarizations. A different insertion loss is obtained for each TA phase shift. Unit-cells are printed on composite flexible dielectric substrate (Dupont Pyralux).

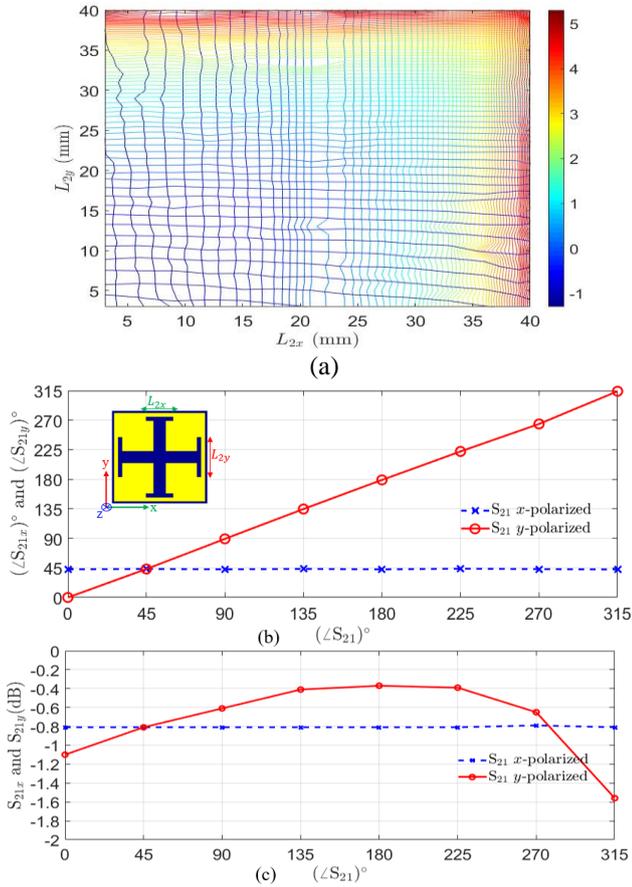


Figure 2: HFSS simulation: (a) 3D normalized susceptances b_x and b_y vs L_2 , (b) simulated $\angle S_{21x}$ and $\angle S_{21y}$ vs desired $\angle S_{21}$ (c) S_{21x} and S_{21y} (dB) at desired $\angle S_{21}$.

The four stacked anisotropic layers achieve a full transmission phase coverage of 360° .

In fact, the polarizations must be orthogonal for two beams of the same coverage and frequency band. The fig.2a shows the contours of normalized susceptances b_x and b_y of one the four layers as a function of two varying arm lengths of

the GJC, namely L_{2x} and L_{2y} (see [2] for details). The good orthogonality between the two sets of contours demonstrate that susceptances associated with x and y polarizations can be adjusted independently over a broad range of values. Although the susceptances, and therefore the phases, of the unit cell can be varied continuously, the TA can be efficiently designed by using a 3-bit phase quantization for each polarization, for a total of 64 possible phase states. Each cell was simulated with Ansys HFSS using a periodic boundary condition (PBC) (master-slave) and de-embedded Floquet ports. The frequency response of the broadband unit-cell were demonstrated in [2].

This Fig.2b illustrates two examples of achievable $\angle S_{21x}$ and $\angle S_{21y}$ simulated phases with respect to the desired ones. In this example, the phase of S_{21x} is fixed to 45 degrees and the 8 phase states of S_{21y} are achievable. Fig. 2c shows the corresponding insertion losses for these 8 states. The blue curve shows that S_{21x} remains constant while S_{21y} varies. It can be seen that the unit cell's insertion loss varies between 0.4 dB and 1.6 dB, depending on the applied phase.

3 Description of the TA-GS Algorithm

The HTA phase shift distribution is the component of interest allowing to synthesize the targeted far-field pattern. In order to present the proposed synthesis approach, the input incident wave has to be known.

For evaluating the performance of TA-GS algorithm and for the sake of simplicity, a "centered-circle flat-top" radiation pattern is demonstrated in this paper. In order to implement the discrete Fourier transform used for the TA-GS algorithm shown in Fig.3, we perform a zero-padding in order to improve pattern resolution in visible uv-plane then apply the FFT operation as required by the Nyquist sampling theorem. The design frequency is 20 GHz. At that frequency the size of the TA is $10.4\lambda \times 10.4\lambda$. Therefore, the numerical results presented here are for a TA of 52×52 cells.

A first validation study of the TA-GS algorithm has been performed with the TA illuminated with a theoretical Gaussian beam. The waist of this Gaussian beam has been varied to determine the required beamwidth of reference incident wave distribution illuminating the HTA. For a given polarization, either parallel (\parallel) or perpendicular (\perp), the equations below describe the iterations steps of the TA-GS procedure, as also illustrated in the flowchart diagram in Fig.3. Here, (x,y) refers to coordinates on unit cells in the TA plane and (u,v) to direction cosines in the far-field. Symbol " \circ " in the following equations indicates the Hadamard product.

$$C(u, v) = I_0(u, v) \circ \exp(j\Psi_0(u, v)) \quad (\text{Eq0})$$

$$\mathcal{F}^{-1}\{C(u, v)\} = E_B(x, y) \circ \exp(j\psi_B(x, y)) \quad (\text{Eq1})$$

$$\Delta\varphi = \psi_i(x, y) - \psi_B(x, y) \quad (\text{Eq2})$$

$$\psi_B^c(x, y) = \Delta\varphi(x, y) + \psi_i(x, y) \quad (\text{Eq3})$$

$$c(x, y) = E(x, y) \circ \exp(j\psi_B^c(x, y)) \quad (\text{Eq4})$$

$$E(x, y) = E_i(x, y) \circ T(x, y)$$

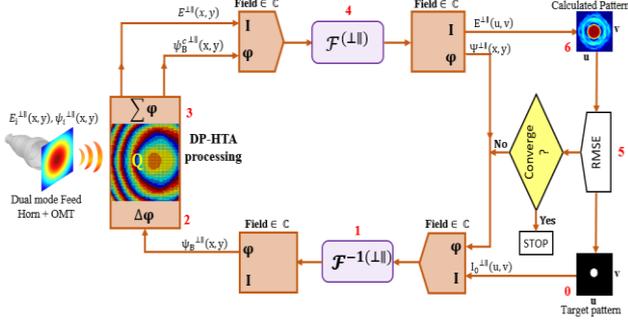


Figure 3: Workflow of the Dual-polarized TA-GS algorithm.

$$\begin{aligned} \widehat{E}(u, v) \circ \exp(j\Psi(u, v)) \\ = \mathcal{F}\{E(x, y) \\ \circ \exp(j\psi_B^c(x, y))\} \quad (\text{Eq5}) \end{aligned}$$

$$RMSE = \left(\sum_{i,j} [\widehat{E}(u, v) - I_0(u, v)]^2 \right)^{0.5} \quad (\text{Eq6})$$

Step 0: Specification of an initial input pattern, loaded as the amplitude distribution $I_0(u, v)$ of the desired far-field pattern. The phase distribution $\Psi_0(u, v)$ can be set to zero for the first iteration. See (Eq0).

Step 1: Back propagation from the far field to the HTA plane is performed with (Eq1).

Step 2: The HTA processing consists of three major operations in the spatial domain:

(a) $\Delta\varphi$ is the phase shift distribution applied by the HTA cells, that is, the difference between the phase of the incident wave on the HTA and the phase at the output of the HTA, as shown in equation (Eq2).

(b) The Q operator quantizes the $\Delta\varphi$ phase shifts into eight phase levels based on 3-bit quantization.

(c) A constant is added to the quantized HTA phase shift distribution in order to move the unit-cell with the best insertion loss at the center of the HTA. This ensures maximum power transfer. The related transmission coefficient magnitude distribution $T(x, y)$ obtained from the data collected from Fig.2c, is also determined.

Step 3: $\psi_B^c(x, y)$ calculated with (Eq3) provides the corrected backward propagator phase. The resulting field at the HTA output is obtained with (Eq4), where $E(x, y)$ is the amplitude distribution resulting from the incident wave $E_i(x, y)$ multiplied with the phase-dependent HTA transmission coefficient distribution $T(x, y)$.

Step 4: Next, the HTA output field distribution is transferred to the far-field (u, v) domain by using the fast Fourier transform (FFT according to (Eq5), where $\mathcal{F}\{\cdot\}$ denotes the FFT operation; $\widehat{E}(u, v)$ and $\Psi(u, v)$ are respectively the amplitude and phase distributions.

Step 5: The difference between the estimated $\widehat{E}(u, v)$ and the target $I_0(u, v)$ patterns with a given threshold namely

the normalized root-mean-square error (RMSE) which is used as a metric to determine the convergence.

Step 6: The TA-GS process is repeated iteratively until the goal (e.g., maximum iteration number or allowed RMSE is reached) is achieved.

4 Numerical results

In this section, we report numerical examples to validate the proposed method.

Here, the primary goal is to determine the optimal HTA phase distribution that can achieve a centered flat-top circular radiation pattern, with minimum sidelobes and ripples in the main beam. For demonstration, a 52×52 square array-antenna with an inter-element spacing of 0.2λ is chosen. The incident wavefront quality is an important factor, as it defines the accuracy of final radiation pattern. It depends on the distance of the HTA from the primary source, which is a dual mode horn antenna fed by an orthomode transducer (OMT). The field characteristics such as edge field intensity, edge illumination, half power beam width, (E, EI and HPBW) have been initially determined through a theoretical approach using Gaussian beam. Subsequently, the dual mode horn antenna is design in Ansys HFSS to provide the required incident wavefront. This is illustrated in Fig4.a and Fig4b for amplitude and phase distribution respectively.

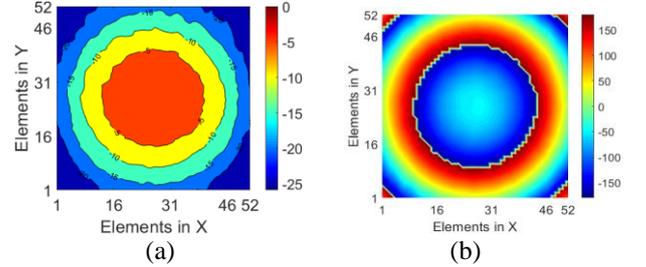
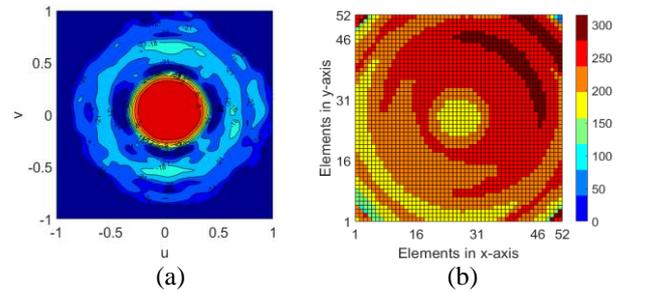
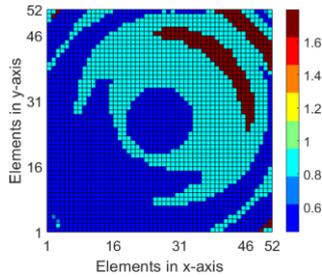


Figure 4: Feed antenna field distribution in the HTA input plane : (a) amplitude (dB), (b) phase ($^{\circ}$).

The HTA is placed at the focal distance of 170 mm from the dual-polarized feed antenna in order to obtain the desired edge field intensity. The amplitude distribution exhibits a half power beam width (HPBW) of 13° , while the required edge illumination $EI = -11$ dB, as magnitude of the taper allows acceptable spillover losses and sidelobes in the HTA far field.





(c)

Figure 5: Results of the synthesis of a centered circular flat-top Far-field pattern: (a) amplitude of far-field pattern, (b) HTA phase-shift distribution, (c) HTA cells insertion loss distribution in dB.

The realized maximum sidelobe level is approximately -18 dB. The results show that the HTA-based optimum phase-shift and insertion loss distribution have a very smooth variation, leading to an efficient beam focusing.

5. Conclusion

In this study, we apply the TA-GS algorithm for dual-polarized beam shaping of concentric beams by a holographic-based dual-polarized transmitarray. First, by designing an anisotropic unit-cell, we were able to numerically demonstrate the generation of dual-polarized flat-top concentric beams with the same HTA aperture using a dual mode horn antenna. TA-GS algorithm features a rapid and robust approach. In this approach, sidelobe level and ripples are minimized inherently. The fabrication of a prototype to validate the proposed approach is underway.

6 References

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