

TIME AND FREQUENCY ACTIVITIES AT THE U.S. NAVAL OBSERVATORY

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Abstract

The U.S. Naval Observatory (USNO) has provided timing for the Navy since 1830 and, via DoD Directive 4650.05, is the sole source of timing for the Department of Defense. In cooperation with other institutions, the USNO also provides timing for the United States and the international community. Its Master Clock (MC) is the source of UTC (USNO), USNO's realization of Coordinated Universal Time (UTC), which has stayed within 5 ns rms of UTC since 1999 and within 4 ns rms in 2010. The data used to generate UTC (USNO) are based upon 69 cesium and 26 hydrogen maser frequency standards in four buildings at two sites. USNO disseminates time via voice, telephone modem, Network Time Protocol (NTP), GPS, and Two-Way Satellite Time Transfer (TWSTT). To meet space limitations, this document will describe only the timescale algorithm and GPS time transfer precision. Further details and explanations of our services can be found online at <http://www.usno.navy.mil/usno>.

I. Time Generation

The most important part of USNO's Time Service Department is its staff, which currently consists of 32 positions. Of these, the largest group, about 40% of the staff, is directly involved in time transfer. The rest are fairly evenly divided between those who service the clocks, those who monitor them, and those who are working to develop new ones.

Before averaging data to form a timescale, real-time and postprocessed clock editing is accomplished by analyzing deviations in terms of frequency and time; all the clocks are detrended against the average of the best detrended cesiums [1]. A maser average represents the most precise average in the short term, and the detrending ensures that it is equivalent to the cesium average over periods exceeding a few months. A.1 is USNO's operational timescale; it is dynamic in the sense that it weights recent maser and cesium data by their inverse Allan variance at an averaging time (τ) equal to the age of the data. Plottable files of both A.1 and the maser mean are available below <http://tycho.usno.navy.mil>.

UTC (USNO) is created by frequency-steering the A.1 timescale to UTC using a steering strategy called "gentle steering" [2-4], which minimizes the control effort used to achieve the desired goal, although at times the steers are so small that they are simply inserted. To realize UTC (USNO) physically, we use the one pulse per second (1-PPS) output of a frequency divider fed by a 5 MHz signal from an Auxiliary Output Generator (AOG). The AOG creates its output from the signal of a cavity-tuned maser steered to a timescale that is itself steered to UTC [2-5]. The MC has a backup maser and an AOG in the same environmental chamber. On 29 October 2004, we changed the steering method so that state estimation and steering are achieved hourly with a

Kalman filter with a gain function as described in [6]. A second master clock (mc), duplicating the MC, is located in an adjacent chamber. In a different building, we have the same arrangement for a third mc, which is steered to the MC. Its backup AOG is steered to a mean timescale, based only on clocks in that building, which is itself steered to the MC.

The operational unsteered timescale (A.1) is based upon averaging only the better clocks, which are first detrended using past performance. As a result of a study conducted in 2000 [8], we have widened the definition of a “good clock” and are recharacterizing the clocks less frequently, and new methods of clock characterization are under development [9]. We are also continuing to work on developing algorithms to combine optimally the short-term precision of the masers with the longer-term precision of the cesiums and the accuracy of International Atomic Time (TAI) itself, which is frequency-calibrated using the primary (fully calibrated) frequency standards operated by other institutions. It is planned to implement an algorithm that steers the MC hourly and tightly to a timescale based only upon masers, which are individually or collectively steered to a cesium-only timescale that itself is steered to UTC using the information in the Circular T [6, 10]. The steered cesium-only timescale is based upon a Kalman-filter [11]. Individual masers would be steered to the cesium-only timescale before being averaged to create the maser-only timescale.

Figure 1 shows how UTC (USNO) has compared to UTC and also how its fractional frequency has compared to the unsteered maser mean, relative to an overall constant offset, and Figure shows how GPS time and GPS’s delivered prediction of UTC(USNO) appear to the user.

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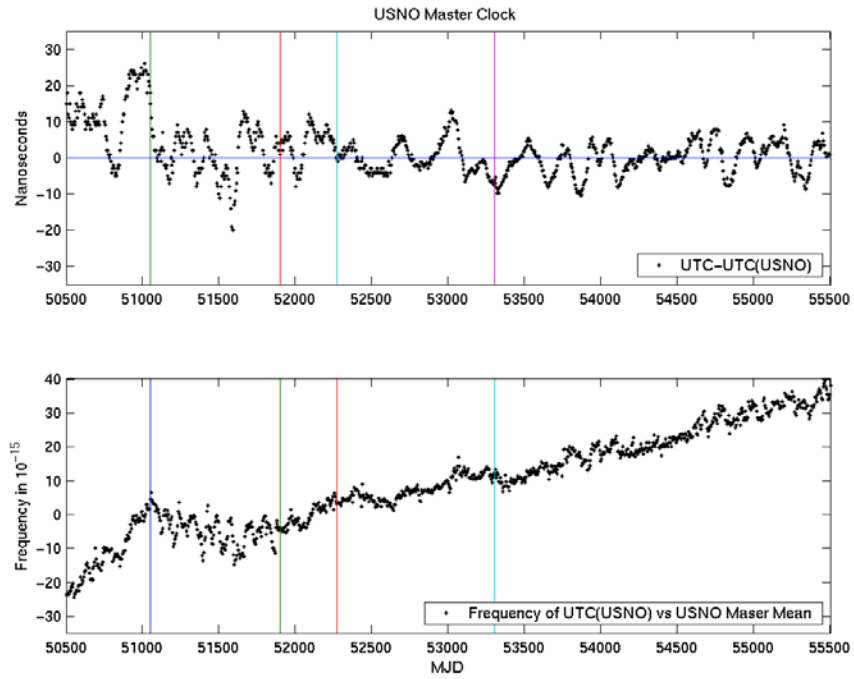


Figure 1. Interplay between the time and fractional frequency stability of the USNO Master Clock, from February, 1997 to the present.

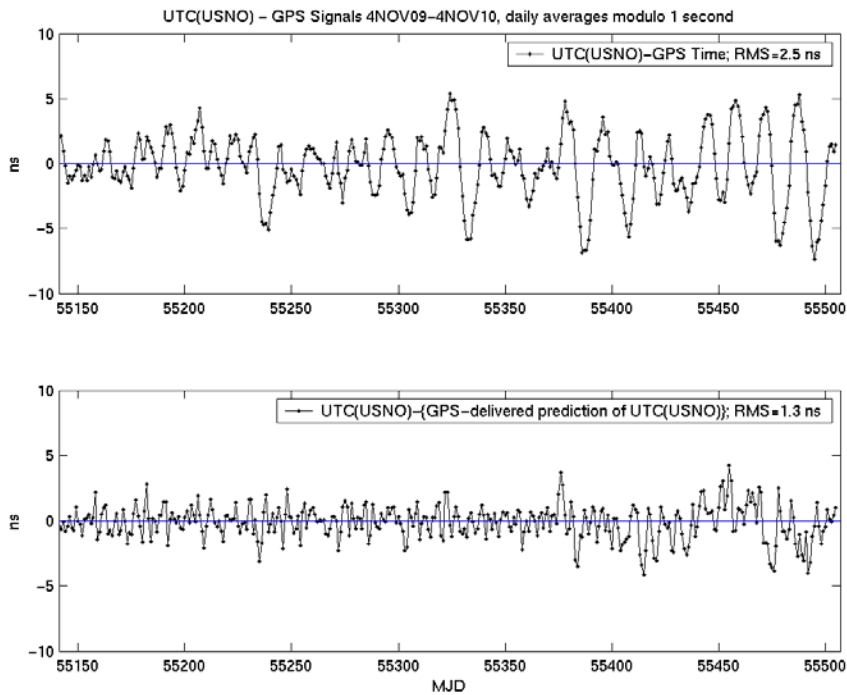


Figure 2. Recent daily averages of UTC (USNO) minus GPS Time and UTC minus GPS's delivered prediction of UTC (USNO).